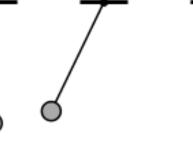
Day 24 - Driven Oscillations

Resonance in a driven pendulum

system. \longrightarrow

Source: Wikipedia



Announcements

- Midterm 1 is still being graded
- Homework 6 is due next Friday
- Homework 7 is posted, due next Friday
 - Final project check-in #1
- Danny will be out this Wednesday
 - Class will be on zoom https://msu.zoom.us/j/92295821308
 - passcode: phy321
 - No office hours Wednesday

Seminars this week

Most of MSU folks are at APS Global Physics Summit

WEDNESDAY, March 19, 2025

- Astronomy Seminar, 1:30 pm, 1400 BPS, Alex Rodriguez, University of Michigan, *Galaxy clusters, cosmology, and velocity dispersion*
- FRIB Nuclear Science Seminar, 3:30pm., FRIB 1300 Auditorium, Dr. Pierre Morfouace of CEA-DAM, *Mapping the new asymmetric fission island with the R3B/SOFIA setup*

THURSDAY, March 20, 2025

Colloquium, 3:30 pm, 1415 BPS, Guillaume Pignol, University of Grenoble, *Ultracold neutrons: a precision tool in fundamental physics*

Reminders

We solved the damped harmonic oscillator equation:

$$\ddot{x}+2eta\dot{x}+\omega_0^2x=0$$

We chose a solution (ansatz) of the form

$$x(t) = C_1 e^{rt} + C_2 e^{rt}$$

and computed the roots of the characteristic equation:

$$r^2+2eta r+\omega_0^2=0$$

We found the roots to be:

$$r=-eta\pm\sqrt{eta^2-\omega_0^2}$$

Weak Damping

We found that when $\beta^2 < \omega_0^2$, the roots are complex:

1

$$r=-eta\pm i\sqrt{\omega_0^2-eta^2}$$

This means that the solution is oscillatory:

$$x(t)=e^{-eta t}\left(\,C_1\cos(\sqrt{\omega_0^2-eta^2}t)+C_2\sin(\sqrt{\omega_0^2-eta^2}t)\,
ight)$$

The solution is a damped oscillation with frequency $\omega_1 = \sqrt{\omega_0^2 - \beta^2}$.

Strong Damping

When $\beta^2 > \omega_0^2$, the roots are real:

$$r=-eta\pm\sqrt{eta^2-\omega_0^2}$$

This means that the solution is not oscillatory:

$$x(t) = C_1 e^{r_1 t} + C_2 e^{r_2 t}$$

where $r_1=-eta+\sqrt{eta^2-\omega_0^2}<0$ and $r_2=-eta-\sqrt{eta^2-\omega_0^2}<0.$

The solution is the sum of two exponentials with different decay rates.

Critical Damping

When $\beta^2 = \omega_0^2$, the roots are real and equal (repeated roots):

$$r=-eta$$

This means that the solution is not oscillatory, but also that our ansatz is not sufficient. The correct form of the solution is:

$$x(t)=(C_1+C_2t)e^{-eta t}$$

In most cases, we will work with weak damping.

Next week, we can choose what to do in class. What would you like to do?

- 1. Fourier Series for solving ODEs (currently scheduled)
- 2. Pathways to Chaos (build off oscillations)
- 3. Collisions and Conservation Laws (momentum and angular momentum)
- 4. Calculus of Variations (spend more time on this?)
- 5. Other ideas?

What do we expect the phase space diagram $(x \lor \dot{x})$ to look like for a weakly damped

harmonic oscillator?

- 1. A set of ellipses
- 2. A set of spirals
- 3. Depends on how weak the damping is
- 4. Depends on the total energy
- 5. More than one of the above

The driven harmonic oscillator equation is:

$$\ddot{x}+2eta\dot{x}+\omega_0^2x=f(t)$$

with $w_0^2 = k/m$ and $2\beta = b/m$. What is the dimension of the driving force f(t)?

- 1. Force (Newtons, N)
- 2. Force per unit second (N/s)
- 3. Force per unit length (N/m)
- 4. Force per unit mass (N/kg)

The driven harmonic oscillator equation is:

$$\ddot{x}+2eta\dot{x}+\omega_0^2x=f(t)$$

This ODE is a _____ differential equation.

- 1. linear
- 2. nonlinear
- 3. first-order
- 4. second-order
- 5. more than one of the above

Example: Sinusoidal Driving Force

Let $f(t) = f_0 \cos(\omega t)$, so that the driven harmonic oscillator equation is:

$$\ddot{x}+2eta\dot{x}+\omega_0^2x=f_0\cos(\omega t)$$

Note: $\omega \neq \omega_0$

Note that if the driving follows a sine wave, then we have:

$$\ddot{y}+2eta\dot{y}+\omega_0^2y=f_0\sin(\omega t)$$

Interesting, $e^{i\omega t} = \cos(\omega t) + i\sin(\omega t)$, let try to work with z(t) = x(t) + iy(t).

We found that the square amplitude of the driven harmonic oscillator is:

$$\Lambda^2=rac{f_0^2}{(\omega_0^2-\omega^2)^2+4eta^2\omega^2}$$

When is the amplitude of the driven oscillator maximized?

- 1. When the driving frequency (ω) is far from the natural frequency (ω_0)
- 2. When the driving frequency (ω) is close to the natural frequency (ω_0)
- 3. When the damping (2β) is weak
- 4. When the damping (2β) is strong
- 5. Some combination of the above