# Day 27 - Introduction to Chaos

#### **Sprott Attractor**

$$egin{aligned} \dot{x} &= y + axy + xz \ \dot{y} &= 1 - bx^2 + yz \ \dot{z} &= x - x^3 - y^2 \ a &= 2.07 \quad b = 1.79 \end{aligned}$$

https://www.dynamicmath.xyz/strang e-attractors/



### Announcements

- Midterm 1 (problems 2 and 3) is graded
  - Problem 1 is still being graded
- Homework 7 is due Friday
  - No homework next week
- Midterm 2 will be assigned next Monday (due 18 April)
  - Second project check-in

#### **Seminars This Week**

#### **MONDAY, March 24, 2025**

 Condensed Matter Seminar 4:10 pm, 1400 BPS, Andrew Kirkpatrick, MSU, Fabrication of orientated NV centres in diamond by ultrafast laser fabrication AND Ankang Liu, MSU Effect of hole-strain coupling on the eigenmodes of semiconductor-based nanomechanical systems

#### **Seminars This Week**

#### WEDNESDAY, March 26, 2025

- Astronomy Seminar, 1:30 pm, 1400 BPS, Bryan Terrazas, Oberlin College, Galaxy evolution and feedback modeling
- FRIB Nuclear Science Seminar, 3:30pm., FRIB 1300 Auditorium, Dr. Jacklyn Gates of Lawrence Berkeley National Laboratory, Toward Pursuing New Superheavy Elements

#### **Seminars This Week**

#### THURSDAY, March 27, 2025

 Special FRIB/MSU Nuclear Science Seminar with Colloquium, 3:30 pm, 1415 BPS, Mandie Gehring, LANL, Measuring Intense Xray Spectra and an Overview of Space Research at Los Alamos National Laboratory

#### **FRIDAY, March 28, 2025**

 IReNA Online Seminar, 2:00 pm, In Person and Zoom, FRIB 2025 Nuclear Conference Room, Jordi José, Technical University of Catalonia, UPC (Barcelona, Spain), Classical novae at the crossroads of nuclear physics, astrophysics and cosmochemistry

## What is Chaos?

At your table, discuss what it means for a system to be chaotic.

- What are some examples of chaotic systems?
- What are some characteristics of chaotic systems?
- How do chaotic systems differ from non-chaotic systems?

Try to come up with two answers to each question to share.



#### Hallmarks of a Classically Chaotic System

- 1. **Deterministic**: The system is governed by deterministic laws (e.g., Newton's laws of motion, a set of differential equations)
- 2. Sensitive to Initial Conditions: A bundle of trajectories that start close together will diverge exponentially over time
- 3. **Non-periodic Behavior**: The system exhibist s complex, non-repeating behavior over time, this might look like "random" behavior, but it is not truly random because it is deterministic

#### Hallmarks of a Classically Chaotic System

- 4. Strange Attractors: The system may have a strange attractor, which is a fractal structure in phase space that the system tends to evolve towards over time
- 5. **Parameter Sensitivity**: The system may be sensitive to small changes in parameters, which can trigger qualitative changes in the system's behavior
- 6. (Sometimes) **Periodic Behavior**: The system may exhibit periodic behavior for certain parameter values, and this might be a signal that the system bifurcates into chaotic behavior for other parameter values

#### **Example 1: Duffing Equation**

 $\ddot{x}+eta\dot{x}+lpha x+\gamma x^3=F_0\cos(\omega t)$ 



**Exhibits Periodic and Chaotic Behavior** 

Illustrates period doubling bifurcations as route to chaos

## Example 2: Lorenz System

$$egin{aligned} \dot{x} &= \sigma(y-x) \ \dot{y} &= x(
ho-z)-y \ \dot{z} &= xy-eta z \end{aligned}$$

Exhibits sensitive dependence on initial conditions Demonstrates the concept of a strange attractor



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### Using solve\_ivp

We will start with the damped driven pendulum as an example. This will illustrate how to use solve\_ivp to solve a system of coupled first-order differential equations.

$$\ddot{ heta}+eta\dot{ heta}+\sin( heta)=A\cos(\omega_D t)$$

We can rewrite this as two first-order equations:

$$\dot{ heta} = \omega \ \dot{\omega} = -eta \omega - \sin( heta) + A\cos(\omega_D t)$$

## Using solve\_ivp

To use solve\_ivp , we write a function for the derivatives:

```
def damped_driven_pendulum(t, y, beta, A, omegaD=1):
    theta, omega = y
    dtheta_dt = omega
    domega_dt = -np.sin(theta) - beta * omega + A * np.cos(omegaD*t)
    return [dtheta_dt, domega_dt]
```

## Using solve\_ivp

Now we can use solve\_ivp to solve the system of equations:

```
# Parameters that define the system
beta = 0.5
A = 1.0
omegaD = 2*np.pi
# Time span for the simulation
t_span = (0, 100)
# Initial conditions: [theta, omega]
y0 = [6, 0]
# Time points where we want the solution
t_eval = np.linspace(t_span[0], t_span[1], 10000)
# Solve the system of equations
solution = solve_ivp(damped_driven_pendulum, t_span, y0, args=(beta, A, omegaD), t_eval=t_eval)
```

## **Damped Driven Pendulum**

#### Long Term Behavior is Periodic



"Period-1" Dynamics is a term to indicate there's a single frequency governing the motion

Phase space plots can provide a better window into the system's behavior